



# Multiloop computation in perturbative QCD : technological advancement and automation

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**Narayan Rana**

DESY, Zeuthen

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DESY-RISC collaboration

J. Ablinger, J. Blümlein, P. Marquard, C. Schneider

International school of subnuclear physics, Erice, Sicily

*Success of a theory lies in absolute predictions of the experiments.*

The Standard Model is the most successful theory in describing the elementary particles and their fundamental interactions, due to combined effort from both the magnificent experiments like Tevatron, HERA, LHC etc. and precise theory predictions, namely perturbative calculations.

### Tevatron

the top quark  
fundamental laws  $\sim 10\%$

agreement with NLO  
theory predictions

### LHC

the Higgs boson  
fundamental laws  $\sim 5\%$

agreement with NNLO  
theory predictions

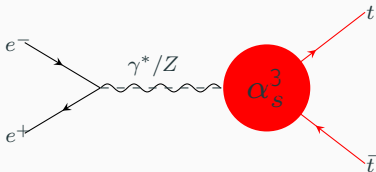
### FCC/ILC

BSM physics?!  
more precision!

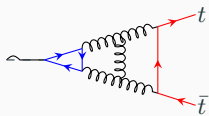
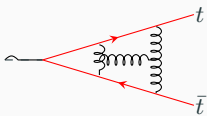
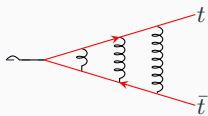
More precise theory  
predictions needed!

Here we present a brief overview on the generic procedure to compute perturbative QCD corrections, mainly pure virtual corrections. We consider a particular process namely top pair production at electron-positron colliders.

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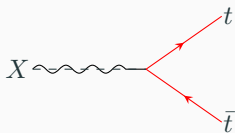
+ many more

# Notation

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## The process

We consider the decay of a color neutral massive particle to a pair of heavy quark of mass  $m$ .



## Notation

$$X(q) \rightarrow t(q_1) + \bar{t}(q_2)$$

$$X = V, A, S, P$$

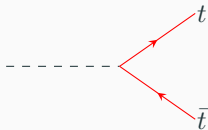
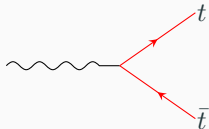
$$s = \frac{q^2}{m^2} = -\frac{(1-x)^2}{x}$$

## The general structure

Vector and Axial Vector

$$V: -i\delta_{ij}v_Q \left( \gamma^\mu F_{V,1} + \frac{i}{2m} \sigma^{\mu\nu} q_\nu F_{V,2} \right)$$

$$A: -i\delta_{ij}a_Q \left( \gamma^\mu \gamma_5 F_{A,1} + \frac{1}{2m} q^\mu \gamma_5 F_{A,2} \right)$$



Scalar and Pseudo Scalar

$$-\frac{m}{v} \delta_{ij} \left[ s_Q F_S + ip_Q \gamma_5 F_P \right]$$



## Computational details

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## The generic procedure

$$d = 4 - 2\epsilon$$

- Draw the Feynman diagrams -> QGRAF [Nogueira]

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- Now the general form

$$\int \frac{d^d l_1}{(2\pi)^{d/2}} \frac{d^d l_2}{(2\pi)^{d/2}} \frac{d^d l_3}{(2\pi)^{d/2}} \frac{\text{const} \times \text{Poly}(s) \times \text{DotProduct}(l_1, l_2, l_3, q_1, q_2)}{l_1^2 l_2^2 l_3^2 \cdots (l_2 - p_1)^2 \cdots}$$

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- Decomposition of the dot products to obtain scalar integrals

$$\frac{2l \cdot p}{l^2(l-p)^2} = \frac{l^2 - (l-p)^2 + p^2}{l^2(l-p)^2} = \frac{1}{(l-p)^2} - \frac{1}{l^2} + \frac{p^2}{l^2(l-p)^2}$$

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- Numerous identity relations (IBPs) among scalar integrals : reduce number of integrals drastically  $\Rightarrow$  compute the remaining integrals

## Integration by parts identities (IBPs)

- IBPs : reduce the number of integrals to compute [Tkachov, Chetyrkin]

Generalization of Gauss's theorem in  $d$  dimension

Within dimensional regularization, all integrals in  $d$  dimension are well-defined and convergent  $\Rightarrow$  integrand must be zero at boundary

$$\int \prod_{i=1}^l \mathcal{D}^{d_i} \frac{\partial}{\partial l_j^\mu} \left( \frac{v^\mu}{D_1^{n_1} \dots D_m^{n_m}} \right) = 0 \quad \Big|_{v \equiv l, p}$$

Example : Consider

$$\mathcal{I}(n) = \int \frac{d^d l}{(2\pi)^{d/2}} \frac{1}{l^2 (l - p_1)^2 ((l - p_1 - p_2)^2)^n}$$

The identity for  $v \equiv l$  gives a recursion relation

$$\mathcal{I}(n+1) = (-1)^n \frac{(d - (n+3)) \cdots (d-4)(d-3)}{n! s^n} \mathcal{I}(1)$$



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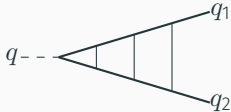
- $\sim 10^6$  identities for our process
- So the problem boils down to solve an algebraic linear system of equations relating the integrals - several programs (AIR, FIRE, Kira, LiteRed ...) available - we use CRUSHER [Marquard, Seidel]

## Computing the master integrals

A scalar integral can be expressed as

$$J(\nu_1, \dots, \nu_n) = \left( (4\pi)^{2-\epsilon} e^{\epsilon\gamma_E} \right)^3 \int \frac{d^d l_1}{(2\pi)^d} \frac{d^d l_2}{(2\pi)^d} \frac{d^d l_3}{(2\pi)^d} \frac{1}{D_1^{\nu_1} \dots D_n^{\nu_n}}$$

For example



$$\begin{aligned} & l_1^2 - m^2, (l_1 - q)^2 - m^2, (l_1 - l_2)^2, \\ & l_2^2 - m^2, (l_2 - q)^2 - m^2, (l_2 - l_3)^2, \\ & l_3^2 - m^2, (l_3 - q)^2 - m^2, (l_1 - q_1)^2 \end{aligned}$$

To evaluate the integral  $\rightarrow$  Feynman parametrization, Mellin-Barnes ...

We use the method of differential equations!

## Using differential equations

The integral is a function of  $d$ ,  $q^2$  and  $m^2$ .

$$\frac{q^2}{m^2} = -\frac{(1-x)^2}{x}$$

$$J(1, 1, 1, 1, 1, 1, 1, 1) \equiv f(d, q^2, m^2) \equiv f(d, x)$$

The idea is to obtain a differential eqn. for the integral *w.r.t.*  $x$  and solve it.

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$$\frac{d}{dx} J_i = \text{some combinations of integrals}$$

⇓ IBP identities

$$= \sum_j c_{ij} J_j$$

$c_{ij}$ 's are rational function of  $d$  and  $x$ .

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$$d_x \begin{pmatrix} J_1 \\ J_2 \\ J_3 \\ J_4 \\ \vdots \\ J_n \end{pmatrix} = \begin{bmatrix} \bullet & \bullet & \bullet & \bullet & \cdots & \bullet \\ \bullet & \bullet & \bullet & \bullet & \cdots & \bullet \\ \bullet & \bullet & \bullet & \bullet & \cdots & \bullet \\ \bullet & \bullet & \bullet & \bullet & \cdots & \bullet \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \bullet & \bullet & \bullet & \bullet & \cdots & \bullet \end{bmatrix} \begin{pmatrix} J_1 \\ J_2 \\ J_3 \\ J_4 \\ \vdots \\ J_n \end{pmatrix}$$

$$d_x \mathbb{J} = \mathbb{A}(d, x) \mathbb{J}$$

## Canonical Basis

The choice of MIs is not unique!

The idea is to find a basis such that the deqs decouple as  $\epsilon \rightarrow 0$

[Kotikov; Henn]

$$d_x \tilde{\mathbb{J}} = \epsilon \tilde{\mathbb{A}}(x) \tilde{\mathbb{J}}$$

Now one can perform Laurent series expansion in  $\epsilon$  and trivially solve the deqs as at each order the homogeneous solutions are constants.

Algorithm to find such basis by [Lee]  
and implementation in `Epsilon`, `Canonica` ...

**Drawback** : Finding such a basis is not always possible.

## Generic Basis

$$d_x \begin{pmatrix} J_1 \\ J_2 \\ J_3 \\ J_4 \\ \vdots \\ J_n \end{pmatrix} = \begin{bmatrix} \bullet & \bullet & \bullet & \bullet & \cdots & \bullet \\ \bullet & \bullet & \bullet & \bullet & \cdots & \bullet \\ \bullet & \bullet & \bullet & \bullet & \cdots & \bullet \\ \bullet & \bullet & \bullet & \bullet & \cdots & \bullet \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \bullet & \bullet & \bullet & \bullet & \cdots & \bullet \end{bmatrix} \begin{pmatrix} J_1 \\ J_2 \\ J_3 \\ J_4 \\ \vdots \\ J_n \end{pmatrix}$$

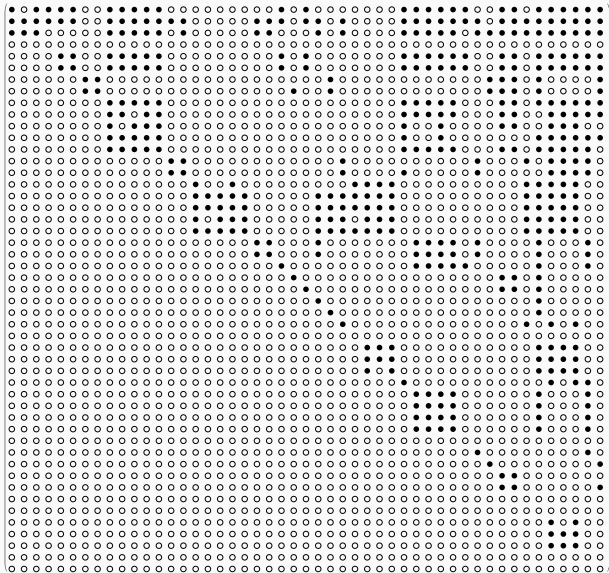


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To solve such a system, it would be best to organize it in such a way that it diagonalizes, or at least it takes a block-triangular form.

$$d_x \begin{pmatrix} J_1 \\ J_2 \\ J_3 \\ J_4 \\ \vdots \\ J_n \end{pmatrix} = \begin{bmatrix} \bullet & \bullet & \bullet & \bullet & \cdots & \bullet \\ 0 & \bullet & \bullet & \bullet & \cdots & \bullet \\ 0 & \bullet & \bullet & \bullet & \cdots & \bullet \\ 0 & 0 & 0 & \bullet & \cdots & \bullet \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \cdots & \bullet \end{bmatrix} \begin{pmatrix} J_1 \\ J_2 \\ J_3 \\ J_4 \\ \vdots \\ J_n \end{pmatrix}$$



Let's consider the 12<sup>th</sup> blob from below

$$\frac{d}{dx} \begin{pmatrix} J_1 \\ J_2 \\ J_3 \end{pmatrix} = \begin{bmatrix} c_{11} & c_{12} & c_{13} \\ c_{21} & c_{22} & c_{23} \\ c_{31} & c_{32} & c_{33} \end{bmatrix} \begin{pmatrix} J_1 \\ J_2 \\ J_3 \end{pmatrix} + \begin{pmatrix} R_1(\epsilon, x) \\ R_2(\epsilon, x) \\ R_3(\epsilon, x) \end{pmatrix},$$

$$c_{11} = \frac{(7 + 6x + 7x^2 - 2d(1 + x + x^2))}{x(1 + x)^2},$$

$$c_{12} = \frac{(-4 + d)(-10 + 3d)}{2(-3 + d)^2(1 + x)^2},$$

$$c_{13} = \frac{(d^2(15 + 8x + 15x^2) + 8(20 + 9x + 20x^2) - 2d(49 + 24x + 49x^2))}{4(-3 + d)^2x(1 + x)^2}, \dots$$

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Each order in  $\epsilon$ -expansion gives a much simpler form

$$\frac{d}{dx} \begin{pmatrix} J_1^{-3} \\ J_2^{-3} \\ J_3^{-3} \end{pmatrix} = \begin{bmatrix} \frac{1}{x} + \frac{2}{1-x} & 0 & \frac{1}{1+x} - \frac{2}{x} - \frac{3}{1-x} \\ -\frac{1}{x} + \frac{2}{1+x} & \frac{1}{1+x} - \frac{1}{x} - \frac{1}{1-x} & \frac{1}{x} - \frac{2}{1+x} \\ \frac{1}{x} + \frac{2}{1-x} & 0 & \frac{1}{1+x} - \frac{2}{x} - \frac{3}{1-x} \end{bmatrix} \begin{pmatrix} J_1^{-3} \\ J_2^{-3} \\ J_3^{-3} \end{pmatrix} + \begin{pmatrix} R_1^{-3}(x) \\ R_2^{-3}(x) \\ R_3^{-3}(x) \end{pmatrix},$$

# Algorithm

- A natural first step is to reduce the system to a higher order equation in a single unknown.  
Note that, the inverse operation is trivial!
- The classical/naive method to achieve this uncoupling is the cyclic vector algorithm. But, it gives a complicated decoupled equation.
- Use smarter uncoupling algorithms, e.g. Zürcher algorithm.
- The homogeneous solutions and uncoupling procedure are similar for each order.
- Now, what remains is to integrate the nonhomogeneous parts.

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Sigma [Schneider], OreSys [Gerhold, Schneider]  
and HarmonicSums [Ablinger, Blümlein, Schneider]

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## Iterated integrals and Harmonic polylogarithms (HPLs)

The nonhomogeneous parts have the following structure

$$\int dx K_{m_n}(x) f(x, \ln(x), \text{Li}_n(x), \dots)$$

$$K_m(x) = \left\{ \frac{1}{x}, \frac{1}{1-x}, \frac{1}{1+x}, \frac{1}{1-x+x^2}, \frac{x}{1-x+x^2} \right\} \equiv \left\{ 0, 1, -1, \{6, 0\}, \{6, 1\} \right\}$$

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On the other hand, given a set of integration kernels  $K_i(t)$ , one can define

$$\mathcal{I}(m_n, \dots, m_1, x) = \int_{x_0}^x K_{m_n}(t) \mathcal{I}(m_{n-1}, \dots, m_1, t) dt$$

For example,

$$\text{Li}_n(x) = \int_0^x \frac{dt}{t} \text{Li}_{n-1}(t)$$

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Hence, one defines a new set of functions, called the HPLs

[Remiddi, Vermaseren, Gehrmann, Goncharov]

$$H(m_n, \dots, m_1, x) = \int_0^x K_{m_n}(t) H(m_{n-1}, \dots, m_1, t) dt$$

Some important properties :

Shuffle algebra, Scaling invariance and integration-by-parts identities

There exists a basis  $\Rightarrow$  Fast numerical evaluation



# Results

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## Results & Checks

- **Computational** : Automation to solve a single scale and first order factorizable system of differential equations.
- **Phenomenological** : We have performed UV renormalization and obtained all the form factors which are necessary to obtain N<sup>3</sup>LO QCD corrections to top pair productions at electron-positron colliders.

$$\underline{F_{V,1}^{(3)}, F_{V,2}^{(3)}, F_{A,1}^{(3)}, F_{A,2}^{(3)}, F_S^{(3)}, F_P^{(3)}}$$

- ✓ We agree with the results from Lee *et al.* obtained using different method
- ✓ The results reproduce the universal infrared structure
- ✓ Chiral Ward identity is satisfied between  $F_{A,i}^{(3)}$  and  $F_P^{(3)}$

## Remarks

- For non-planar contributions, large differential equations  $\sim 50$  MBs!
- Also first-order non-factorizable differential equations appear!  
 $\Rightarrow$  Solutions are **Elliptic polylogarithms**
- A proper generalization for iterative integrals over elliptic polylogarithms is needed!

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### **We are at a crossroad!**

*New mathematical structures are emerging in loop calculations! An entirely new branch of research is opening, putting together computer scientists, mathematicians, particle physicists and string theorists. Maybe what we need now, is a fresh look at the problem with fresh ideas!*

## One-loop and beyond

$$F_{V,i}^{(1)}, F_{A,i}^{(1)} \quad [\text{Arbuzov, Bardin, Leike '92; Djouadi, Lampe, Zerwas '95}]$$

$$F_S^{(1)}, F_P^{(1)} \quad [\text{Braaten, Leveille '80; Sakai '80; Drees, Hikasa '90}]$$

$$F_{V,i}^{(2)}, F_{A,i}^{(2)} \quad [\text{Altarelli, Lampe '93; Ravindran, van Neerven '98; Catani, Seymour '99}]$$

$$F_S^{(2)}, F_P^{(2)} \quad [\text{Gorishnii et. al. '91; Chetyrkin, Kwiatkowski '95; Harlander, Steinhauser '97}]$$

## Two-loop

$$F_I^{(2)} \quad [\text{Bernreuther, Bonciani, Gehrmann, Heinesch, Leineweber, Mastroli, Remiddi '04,'05}]$$

$$F_{V,i}^{(2)}(\mathcal{O}(\epsilon)) \quad [\text{Gluz, Mitov, Moch, Riemann '09}]$$

$$F_I^{(2)}(\mathcal{O}(\epsilon^2)) \quad [\text{Ablinger, Behring, Blümlein, Falcioni, Freitas, Marquard, Rana, Schneider '17}]$$

## Three-loop

$$F_{V,i}^{(3)}|_{\text{large N}} \quad [\text{Henn, Smirnov, Smirnov, Steinhauser '16}]$$

$$F_{V,i}^{(3)}, F_{A,i}^{(3)}, F_S^{(3)}, F_P^{(3)}|_{\text{large N+full } n_l} \quad [\text{Lee, Smirnov, Smirnov, Steinhauser '18}]$$

$$F_{V,i}^{(3)}, F_{A,i}^{(3)}, F_S^{(3)}, F_P^{(3)}|_{\text{large N+full } n_l} \quad [\text{Ablinger, Blümlein, Marquard, Rana, Schneider '18}]$$

Thank you for your attention!